



Science

## LESSENING OF ACTUAL POWER LOSS BY MODIFIED ALGORITHM

Dr. K. Lenin <sup>\*1</sup>

<sup>\*1</sup> Professor, Department of EEE Prasad V.Potluri Siddhartha Institute of Technology, Kanuru,  
Vijayawada, Andhra Pradesh, India



### Abstract

This paper presents a Modified Teaching-Learning-Based Optimization (MTLBO) algorithm for solving reactive power flow problem. Basic Teaching-Learning-Based Optimization (TLBO) is reliable, accurate and vigorous for solving the optimization problems. Also, it has been found that TLBO algorithm slow in convergence due to its high concentration in the accuracy. This paper presents an, Modified version of TLBO algorithm, called as Modified Teaching-Learning-Based Optimization (MTLBO). A parameter called as “weight” has been included in the fundamental TLBO equations & subsequently it increases the rate of convergence. In order to evaluate the proposed algorithm, it has been tested in practical 191 test bus system. Simulation results reveal about the better performance of the proposed algorithm in reducing the real power loss & voltage profiles are within the limits.

**Keywords:** Optimal Reactive Power; Transmission Loss; Modified Teaching Learning.

**Cite This Article:** Dr. K. Lenin (2018). “LESSENING OF ACTUAL POWER LOSS BY MODIFIED ALGORITHM” *International Journal of Research - Granthaalayah*, 6(8), 159-167.  
<https://doi.org/10.29121/granthaalayah.v6.i8.2018.1418>.

### 1. Introduction

Optimal reactive power dispatch problem is one of the difficult optimization problems in power systems & various mathematical techniques [1-7] have been utilized to solve the problem. Recently many types of Evolutionary algorithms [8-9] have been used to solve the reactive power problem. This paper presents a Modified Teaching-Learning-Based Optimization (MTLBO) algorithm for solving reactive power flow problem. Basic Teaching-Learning-Based Optimization (TLBO) [10-16] is reliable, accurate and vigorous for solving the optimization problems. Also it has been found that TLBO algorithm slow in convergence due to its high concentration in the accuracy. This paper presents an, Modified version of TLBO algorithm, called as Modified Teaching-Learning-Based Optimization (MTLBO). A parameter called as “weight” has been included in the fundamental TLBO equations & subsequently it increases the rate of convergence. In order to evaluate the proposed algorithm, it has been tested in practical 191 test bus system. Simulation results reveal about the better performance of the proposed algorithm in reducing the real power loss & voltage profiles are within the limits.

## 2. Objective Function

### Active Power Loss

The objective of the reactive power dispatch is to minimize the active power loss in the transmission network, which can be described as follows:

$$F = PL = \sum_{k \in Nbr} g_k (V_i^2 + V_j^2 - 2V_i V_j \cos \theta_{ij}) \quad (1)$$

Where F- objective function,  $P_L$  – power loss,  $g_k$ -conductance of branch,  $V_i$  and  $V_j$  are voltages at buses i,j, Nbr- total number of transmission lines in power systems.

### Voltage Profile Improvement

For minimizing the voltage deviation in PQ buses, the objective function becomes:

$$F = PL + \omega_v \times VD \quad (2)$$

Where VD - voltage deviation,  $\omega_v$ - is a weighting factor of voltage deviation.

Voltage deviation given by:

$$VD = \sum_{i=1}^{Npq} |V_i - 1| \quad (3)$$

Where Npq- number of load buses

### Equality Constraint

The equality constraint of the problem is represented by the power balance equation, where the total power generation must cover the total power demand and the power losses:

$$P_G = P_D + P_L \quad (4)$$

Where  $P_G$ - total power generation,  $P_D$  - total power demand.

### Inequality Constraints

The inequality constraints in the power system as well as the limits created to ensure system security. Upper and lower bounds on the active power of slack bus ( $P_g$ ), and reactive power of generators ( $Q_g$ ) are written in mathematically as follows:

$$P_{gslack}^{min} \leq P_{gslack} \leq P_{gslack}^{max} \quad (5)$$

$$Q_{gi}^{min} \leq Q_{gi} \leq Q_{gi}^{max}, i \in N_g \quad (6)$$

Upper and lower bounds on the bus voltage magnitudes ( $V_i$ ):

$$V_i^{min} \leq V_i \leq V_i^{max}, i \in N \quad (7)$$

Upper and lower bounds on the transformers tap ratios ( $T_i$ ):

$$T_i^{min} \leq T_i \leq T_i^{max}, i \in N_T \quad (8)$$

Upper and lower bounds on the compensators reactive powers ( $Q_c$ ):

$$Q_c^{min} \leq Q_c \leq Q_c^{max}, i \in N_c \quad (9)$$

Where  $N$  is the total number of buses,  $N_T$  is the total number of Transformers;  $N_c$  is the total number of shunt reactive compensators.

### 3. Basic Teaching-Learning-Based Optimization

Based on the consequence of the influence of a teacher on the output of students in a class, Teaching-Learning-Based Optimization (TLBO) optimization algorithm has been framed. It is a population-based method & there are numbers of different design variables. Different subjects offered to learners and the learners' result is analogous to the "fitness" & it act as different design variables in TLBO. The most excellent solution is analogous to Teacher in TLBO. The algorithm consists of first part "Teacher Phase" and the second "Learner Phase". Learning from the teacher is the "Teacher Phase" means and learning through the interaction between learners is the "Learner Phase". The execution of TLBO as follows,

#### 1) Initialization

Following are the notations used for describing the TLBO:

$L$ : "class size" of the learners;

$C$ : list of the courses offered to the learners to learn;

$MAX IT$ ; number of maximum iterations.

In search space bounded the population  $Y$  is arbitrarily initialized by a by matrix of  $L$  rows and  $C$  columns. In  $i$ th learner . the  $j$ th parameter is assigned values arbitrarily by equation

$$y_{(i,j)}^0 = y_j^{min} + rand \times (y_j^{max} - y_j^{min}) \quad (10)$$

Within the range (0,1) " $rand$ " represents a uniformly distributed arbitrary variable, minimum and maximum value for  $j$ th parameter is represented by  $y_j^{max}$  and  $y_j^{min}$ . For the generation  $g$  parameters of the  $i$ th learner are given by,

$$Y_{(i)}^g = [y_{(i,1)}^g, y_{(i,2)}^g, y_{(i,3)}^g, \dots, y_{(i,j)}^g, \dots, y_{(i,D)}^g] \quad (11)$$

## 2) Teacher Phase

At generation  $g$  the mean parameter  $E_g$  of each subject learners in the class is given as,

$$E^g = [e_1^g, e_2^g, \dots, e_j^g, \dots, e_D^g] \quad (12)$$

The teacher  $X_{Teacher}^g$  with the minimum objective function value of the learner is considered as for respective iteration. Shifting the mean of the learners towards its teacher is done by Teacher phase. An arbitrary weighted differential vector is formed to obtain a new-fangled set of improved learners from the current mean, desired mean parameters and is added to the existing population of learners.

$$Y_{new(i)}^g = Y_{(i)}^g + rand \times (Y_{Teacher}^g - T e_F E^g) \quad (13)$$

The value of mean to be changed is decided by " $T e_F$ " - teaching factor. Value of  $T_F$  can be either 1 or 2. With equal probability the value of  $T e_F$  is decided arbitrarily as,

$$T e_F = round [1 + rand (0.1) \{2 - 1\}] \quad (14)$$

The value of  $T_F$  value is arbitrarily decided by the algorithm using Equation (14). In generation  $g$  if  $Y_{new(i)}^g$  is superior learner than  $Y_{(i)}^g$ , then it swap the inferior learner  $Y_{(i)}^g$  in the matrix.

## 3) Learner Phase

In this phase the mutual interaction tends to augment the knowledge of the learner. The arbitrary inter- action among learners improves the knowledge. For a given learner  $Y_{(i)}^g$  another learner  $Y_{(r)}^g$  is arbitrarily selected ( $i \neq r$ ). In the learner phase the  $i$ th parameter of the matrix  $Y_{new}$  is given as,

$$Y_{(i)}^g = \begin{cases} Y_{(i)}^g + rand \times (Y_{(i)}^g - Y_{(r)}^g) \\ \text{if } f(Y_{(i)}^g) < f(Y_{(r)}^g) \\ Y_{(i)}^g + rand \times (Y_{(r)}^g - Y_{(i)}^g) \text{ otherwise} \end{cases} \quad (15)$$

## 4) Algorithm Termination

After *MAXIT* conditions satisfied the algorithm is terminated.

## 4. Modified Teaching-Learning-Based Optimization (MTLBO) Algorithm

The principles of teaching-learning approach is imitated in Teaching-Learning-Based Optimization (TLBO) & draw analogy with the real class room. Teaching-learning process is an iterative process where in the continuous interaction takes place for the transfer of knowledge. A parameter known as "weight" is added in the Equations (13) and (15) of original TLBO algorithm. In contrast to the original TLBO, while computing the new learner values the part of its previous

value is considered and decided by a weight factor “ $wf$ ” in our Modified Teaching-Learning-Based Optimization (MTLBO) algorithm. During the early stages of the search Individuals are encouraged to sample diverse zones of the exploration space. It is important to adjust the movements of trial solutions finely & they can explore the interior of a relatively small space in the later stages. Value of the weight factor reduced linearly with time from a maximum to a minimum value by,

$$wf = wf_{max} - \left( \frac{wf_{max} - wf_{min}}{\max iteration} \right) * i \quad (16)$$

The maximum and minimum values of weight factor  $w$  are  $wf_{max}$  and  $wf_{min}$ , “ $I$ ” - iteration is the current iteration number and max iteration is the maximum number of iterations.  $wf_{max}$  &  $wf_{min}$  are selected between 0.9 -0.1, respectively. New set of improved learners in the teacher phase can be,

$$Y_{new(i)}^g = wf * Y_{(i)}^g + rand * (Y_{Teacher}^g - Te_F E^g) \quad (17)$$

And in learner phase a set of improved learners are,

$$Y_{new(i)}^g = \begin{cases} wf * X_{(i)}^g + rand \times (Y_{(i)}^g - Y_{(r)}^g) \\ \text{if } f(Y_{(i)}^g) < f(Y_{(r)}^g) \\ wf * Y_{(i)}^g + rand \times (Y_{(r)}^g - Y_{(i)}^g) \text{ otherwise} \end{cases} \quad (18)$$

## 5. Simulation Results

**Modified** Teaching-Learning-Based Optimization (**MTLBO**) algorithm has been tested in practical 191 test system and the following results have been obtained. In Practical 191 test bus system – Number of Generators = 20, Number of lines = 200, Number of buses = 191 Number of transmission lines = 55. Table 1 shows the optimal control values of practical 191 test system obtained by MTLBO method. And table 2 shows the results about the value of the real power loss by obtained by **Modified** Teaching-Learning-Based Optimization (**MTLBO**) algorithm.

Table 1: Optimal Control values of Practical 191 utility (Indian) system by MTLBO method

VG1	1.1000	VG 11	0.9000
VG 2	0.7200	VG 12	1.0000
VG 3	1.0100	VG 13	1.0000
VG 4	1.0100	VG 14	0.9000
VG 5	1.1000	VG 15	1.0000
VG 6	1.1000	VG 16	1.0000
VG 7	1.1000	VG 17	0.9000
VG 8	1.0100	VG 18	1.0000
VG 9	1.1000	VG 19	1.1000
VG 10	1.0100	VG 20	1.1000

T1	1.0000	T21	0.9000	T41	0.9000
T2	1.0000	T22	0.9000	T42	0.9000
T3	1.0000	T23	0.9000	T43	0.9100
T4	1.1000	T24	0.9000	T44	0.9100
T5	1.0000	T25	0.9000	T45	0.9100
T6	1.0000	T26	1.0000	T46	0.9000
T7	1.0000	T27	0.9000	T47	0.9100
T8	1.0100	T28	0.9000	T48	1.0000
T9	1.0000	T29	1.0100	T49	0.9000
T10	1.0000	T30	0.9000	T50	0.9000
T11	0.9000	T31	0.9000	T51	0.9000
T12	1.0000	T32	0.9000	T52	0.9000
T13	1.0100	T33	1.0100	T53	1.0000
T14	1.0100	T34	0.9000	T54	0.9000
T15	1.0100	T35	0.9000	T55	0.9000

Table 2: Optimum real power loss values obtained for practical 191 utility (Indian) system by MTLBO method.

Real power Loss (MW)	MTLBO
Min	149.1213
Max	154.1298
Average	151.2010

## 6. Conclusion

In this paper a novel approach Modified Teaching-Learning-Based Optimization (MTLBO) algorithm used to solve reactive power problem, considering various generator constraints, has been successfully applied. Also it has been found that TLBO algorithm slow in convergence due to its high concentration in the accuracy. The performance of the proposed Modified Teaching-Learning-Based Optimization (MTLBO) algorithm has been tested in **practical 191 test bus system** and simulation results expose about the decrease of real power loss & voltage profiles are within the limits.

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\*Corresponding author.

E-mail address: gklenin @gmail.com

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